

Chapter - 7 : [ROTATIONAL MECHANICS] (घूर्णन यांत्रिकी)

① Vector [VECTOR PRODUCT
CROSS PRODUCT]

② Motion in a straight + plane

③ Newton's Laws of motion (NLM)

④ friction (घर्षण) + Circular motion
घूर्णीय गति

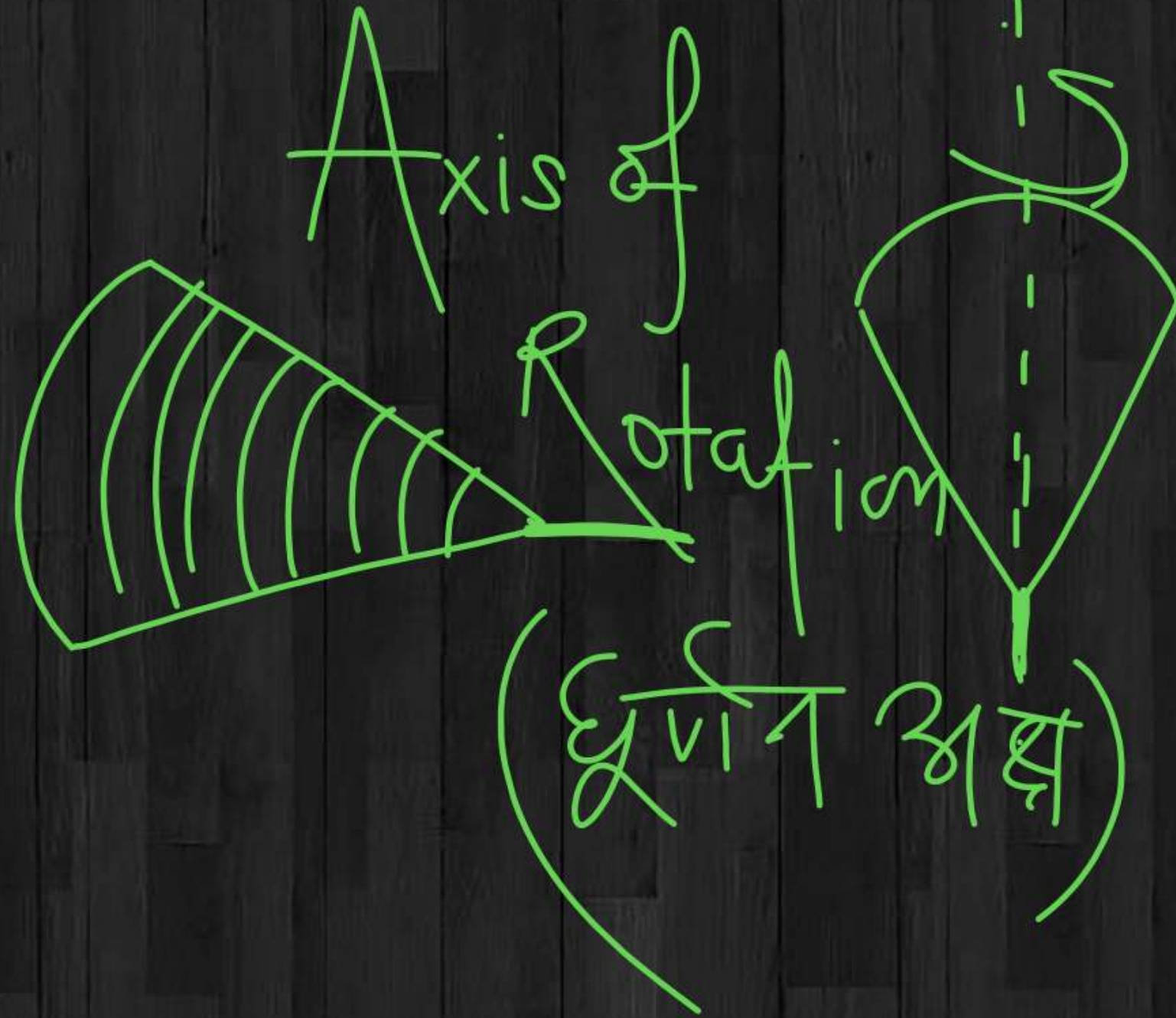
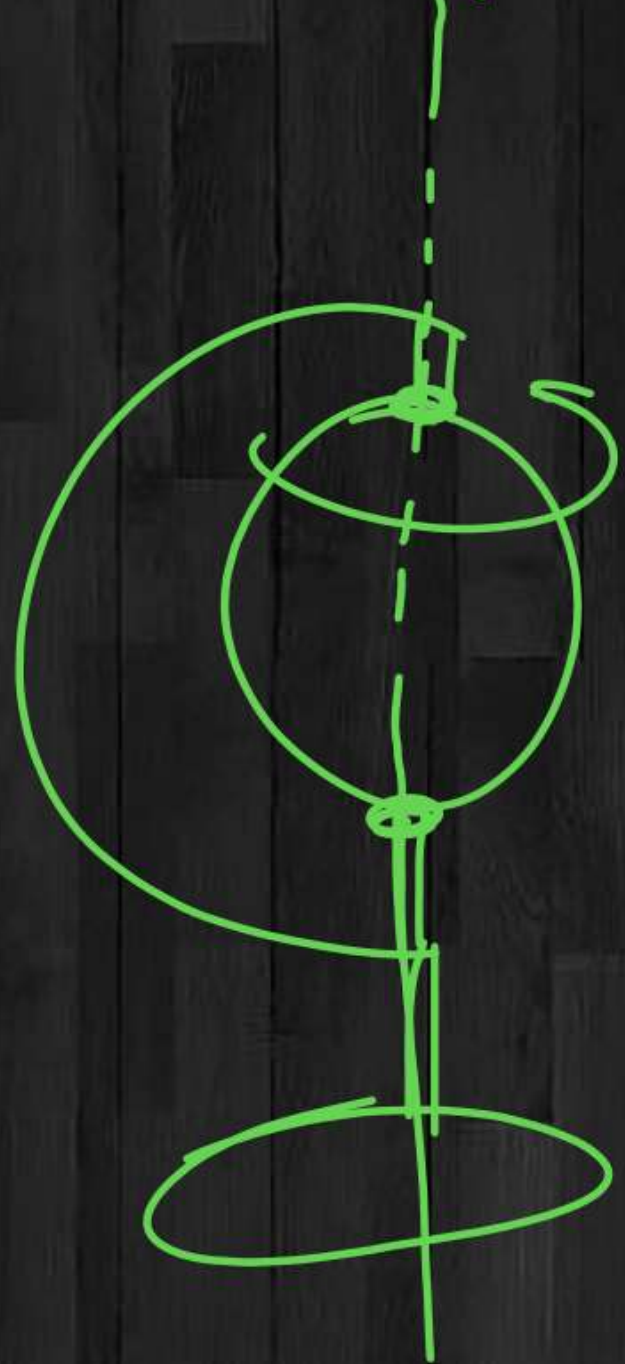
V · U · J

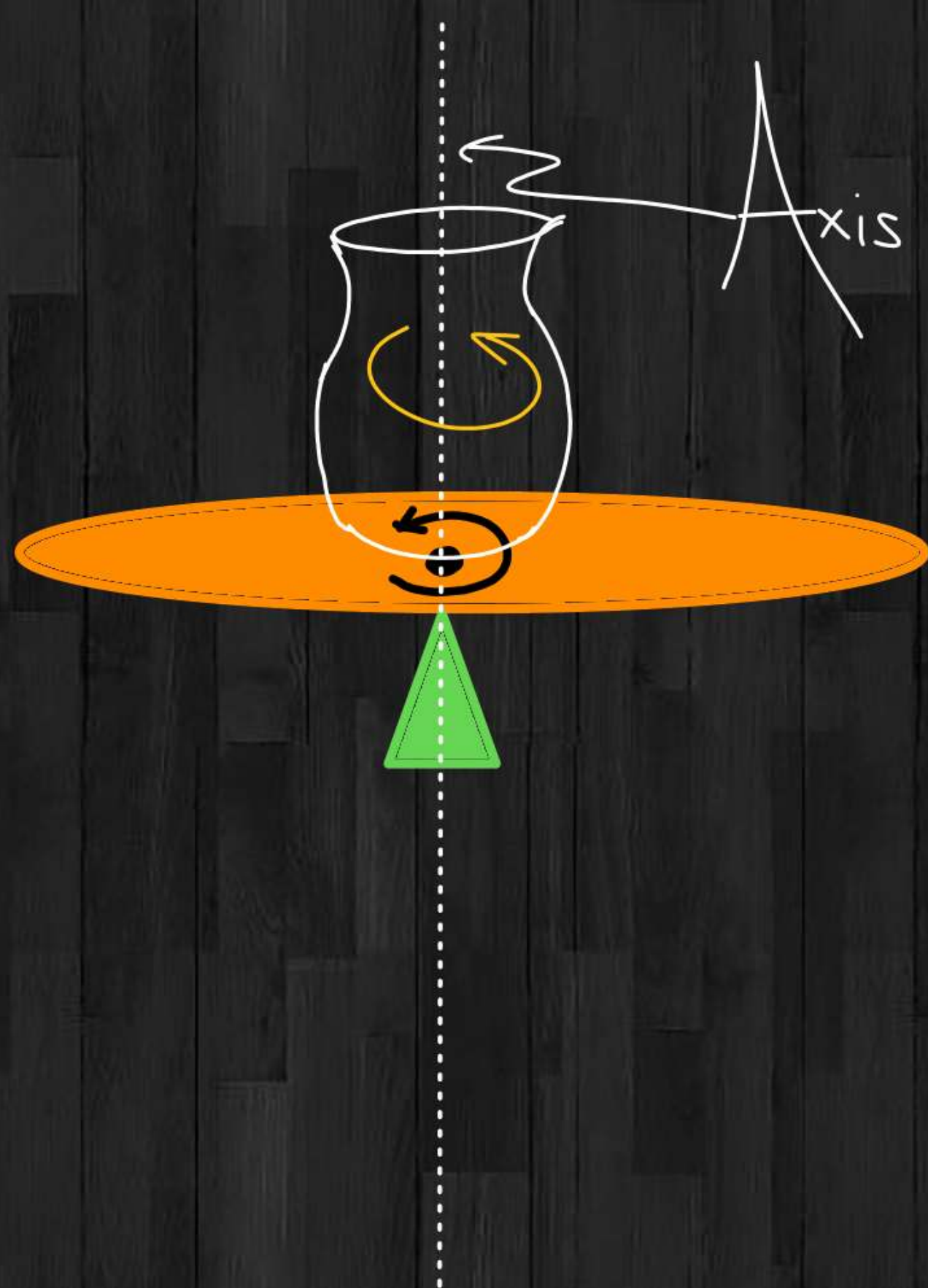
© Conservation of momentum
(संवेग का संरक्षण)

Ⓣ Work = Energy & power.
(कार्य ऊर्जा तथा शक्ति)

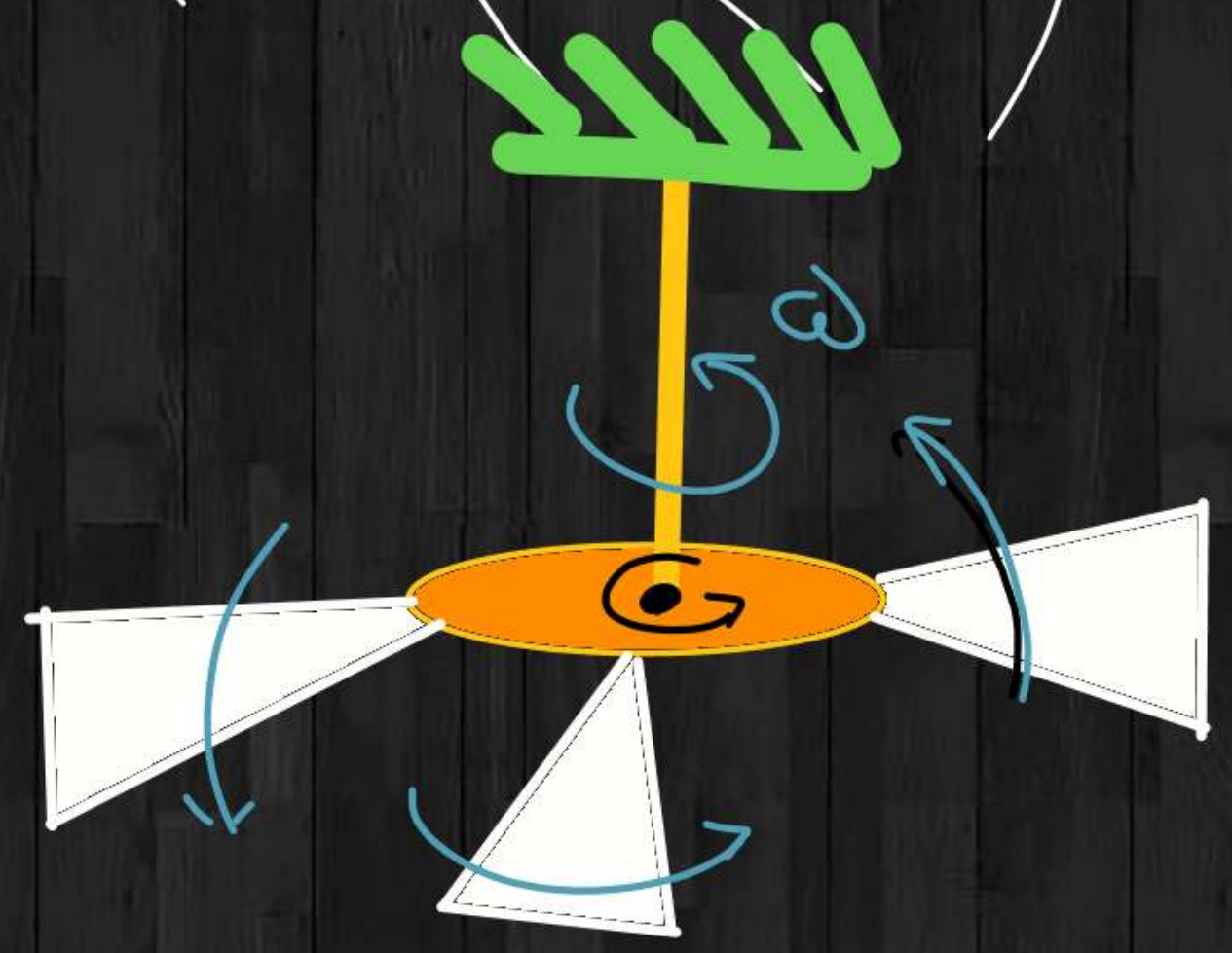


Introduction (परिचय) →





Axis of Rotation (घूर्णन अक्ष)



Centre of gravity (गुरुत्विय केन्द्र)

<1> Centre of mass [द्रव्यमान केन्द्र]

<2> Moment of Inertia (जड़त्व आघूर्ण)

<3> Torque / Moment of force [बल आघूर्ण]

<4> Angular momentum and angular impulse
(कोणिय संवेग तथा आवेग)

5 Newton's Second Law of motion

* Conservation of angular momentum
कोणिय संवेग का संरक्षण

* Impulse-momentum theory

आवेग संवेग प्रमेय

⑥ Rotational motion
(घूर्णन गति)

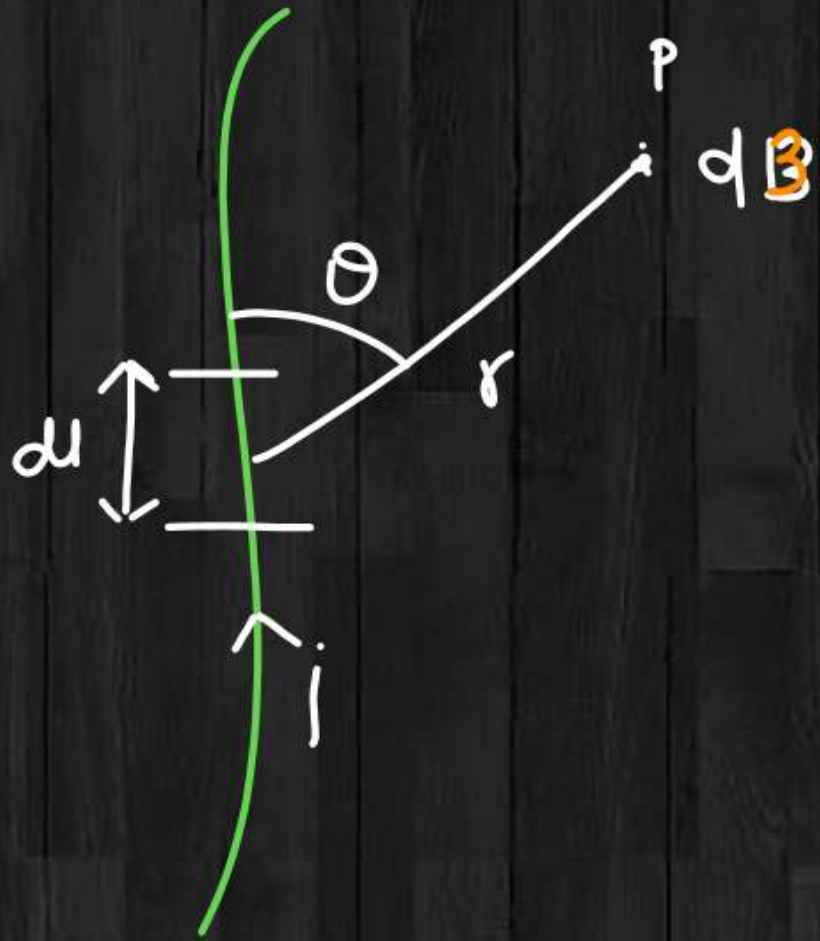
Pure Rotational Motion

Rolling Motion

CASES ↙

Question

BIOT-SAVART LAW [बिओट-सर्वत का नियम]



$$dB \propto i$$

$$dB \propto dl$$

$$dB \propto \sin\theta$$

$$dB \propto \frac{1}{r^2}$$

$$dB \propto \frac{Idl \sin\theta}{r^2}$$

$$dB = \left(\frac{\mu_0}{4\pi} \right) \frac{Idl \sin\theta}{r^2}$$

$$\frac{\mu_0}{4\pi} = \text{नियतांक}$$

$$= 10^{-7} \text{ Tm/A} = 10^{-7} \frac{\text{H}}{\text{m}}$$

$$\mu_0 = 4\pi \times 10^{-7} \frac{\text{H}}{\text{m}}$$

$$= 4\pi \times 10^{-7} \frac{\text{Tm}}{\text{A}} \left[\frac{\omega b}{\text{A} \cdot \text{m}} \right]$$

$$= 4\pi \times 10^{-7} \frac{\text{J}}{\text{Am}}$$

$$\text{Henry} = \frac{\omega b}{\text{A}} = \frac{\text{Tm}^2}{\text{A}} = \frac{\text{N}}{\text{A} \cdot \text{m}}$$

$$\boxed{\text{H} = \frac{\text{Nm}}{\text{A}} = \frac{\text{J}}{\text{A}} = \frac{\omega b}{\text{A}} = \frac{\text{Tm}^2}{\text{A}}}$$

Vector form of Biot-Savart Law

Biot-Savart का सदिश रूप: \rightarrow

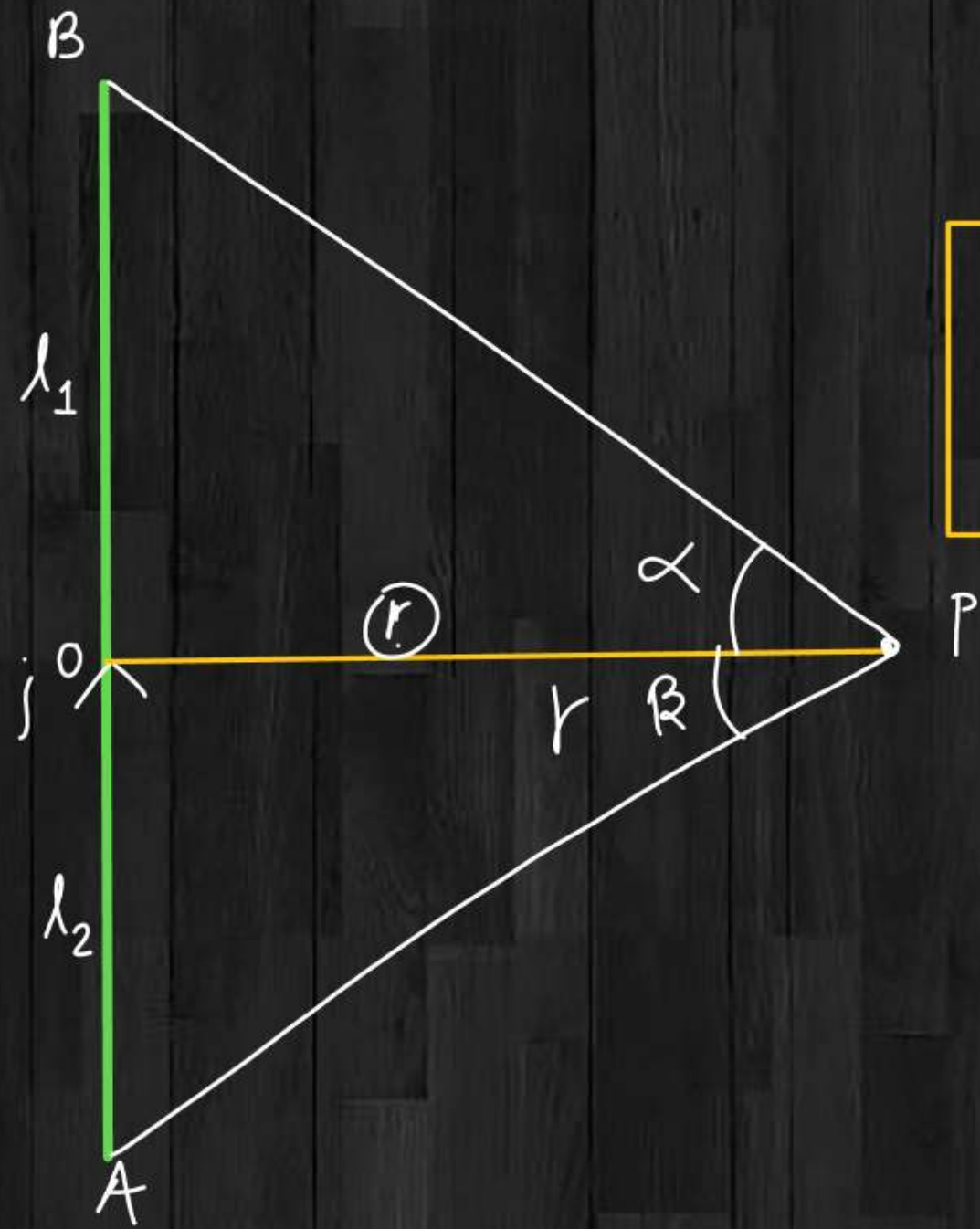
$$\vec{dB} = \frac{\mu_0}{4\pi} \frac{I(\vec{dl} \times \vec{r})}{|\vec{r}|^3}$$

$$\vec{dB} = \frac{\mu_0}{4\pi} \cdot \frac{I(\vec{dl} \times \vec{r})}{r^3}$$

Coulomb's law \rightarrow Vector form: \rightarrow

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \cdot \frac{q_1 q_2}{|\vec{r}|^3} \cdot \vec{r}$$

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{|\vec{r}_2 - \vec{r}_1|^3} (\vec{r}_2 - \vec{r}_1)$$



$$\beta_p = \frac{\mu_0 i}{4\pi r} [\sin \alpha + \sin \beta]$$

Ampere Circuital Law

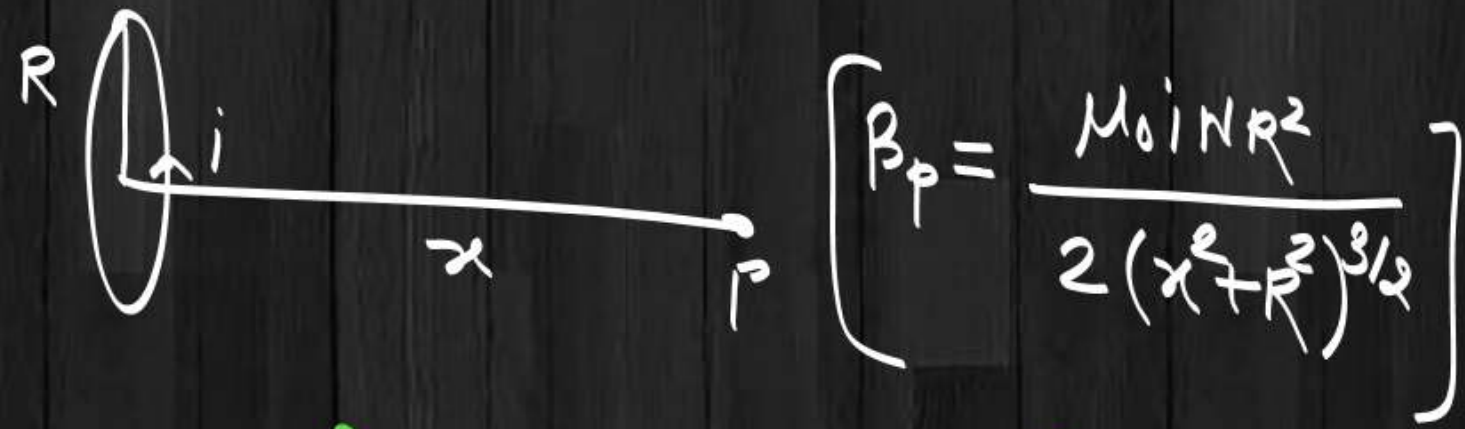
रम्पीयर परिपथीय नियम: \rightarrow

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 i$$

किसी बन्द लूप में चुम्बकीय क्षेत्र का रेखीय समाकलन उससे प्रवाहित कुल धारा के μ_0 गुना के बराबर होता है।

The line integral of magnetic field in a close loop is equal to the μ_0 times of current flow through it.

Application of ACL


$$B_p = \frac{\mu_0 i N R^2}{2(x^2 + R^2)^{3/2}}$$

① अनन्त लम्बाई वाले धारावाही चालक तार के कारण चुम्बकीय क्षेत्र
(Magnetic field due to current carrying ^{long} straight wire)



$$B_p = \frac{\mu_0 i}{2\pi r}$$

